

# Digital Roads Prosperity Partnership Physical Theme

Co-investigators: Prof Abir Al-Tabbaa and Prof Fumiya Iida, University of Cambridge,

Senior Research Associate: Dr Damian Palin, Dr Jie Xu. Industry Researcher: Dr Richard Anvo. PhD student: Mr Samuel Schaefer

Maintaining highway infrastructure is essential for safety and efficiency, yet traditional repair methods are often reactive, costly, labour-intensive, and disruptive to traffic flow. The **Digital Roads Prosperity Partnership** aims to revolutionise highway maintenance by integrating advanced physical and digital technologies.

Digital Roads consists of three interconnected themes: Physical, Digital, and Impact

The **Physical Theme** is developing an **Autonomous Maintenance Plant (AMP)** for highway repair. This initiative focuses on three key research tasks: Development of enhanced physical and digital repair materials; Development of physical and digital robotic crack repair processes; and Development of the digital AMP concept processes. Through the AMP, in collaboration with the Digital and Impact themes, we will achieve faster and more effective pre-emptive road maintenance leading to less disruptions and the extended lifespan of highway infrastructure and enhancing road safety.

## Development physical and digital enhanced repair materials

This work investigates the development of enhanced concrete road repair materials by adding various fibres to two commercial products: Rapid Set (cementitious) and Road Mender (polyurethane). We tested the enhanced materials for extrusion and crack fillability into 3 and 6 mm cracks, mechanical performance through flexural, and compression tests, and effectiveness as repairs using three-point bending (Fig. 1a) and slant shear on concrete with 6 mm cracks. For example, RS enhanced with 0.6% polyvinyl alcohol fibres (1–2 mm in length) demonstrated as a repair under flexure, a 30% increase in ultimate strength and toughness, twice the ductility compared to plain RS (Fig 1b), leading to potentially more durable repairs—extending repair lifespan and reducing maintenance costs.

### Flexural test of repair

Fig. 1 b)

### Flexural repair data

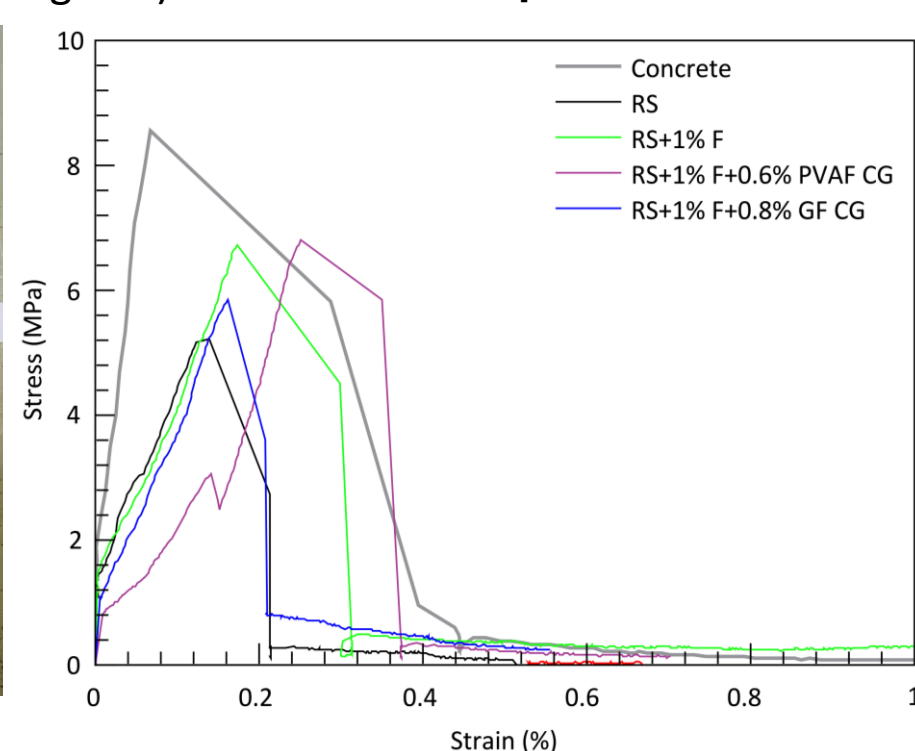


Fig. 1. Mechanical testing of enhanced repair materials: a) Commercial repair materials; a) Flexural test to measure the flexural (bending) strength, properties of the materials; and b) Plot showing the flexural properties of representative materials composed of Rapid Set and fibre additions.

## Development of physical and digital robotic crack repair processes

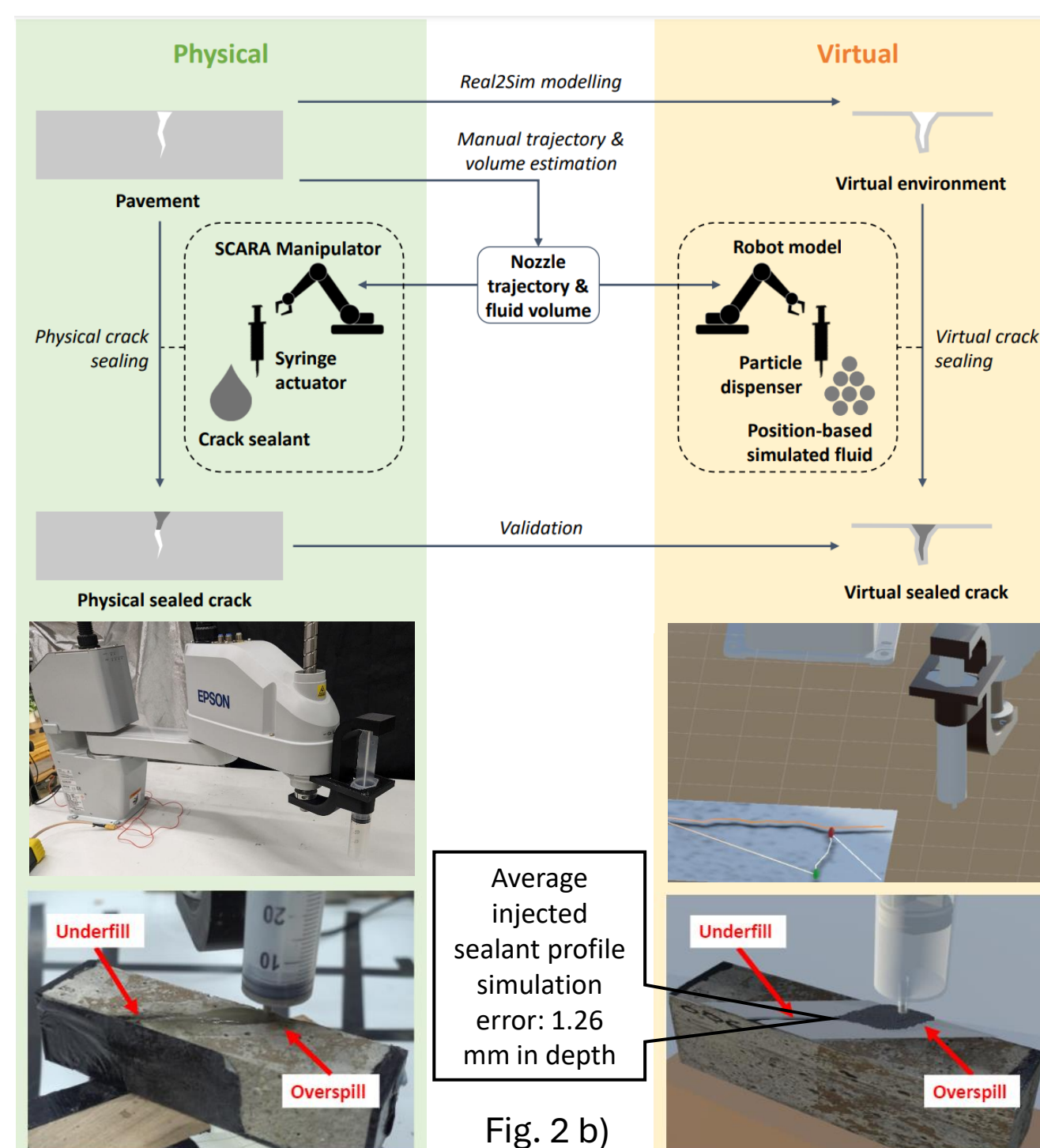
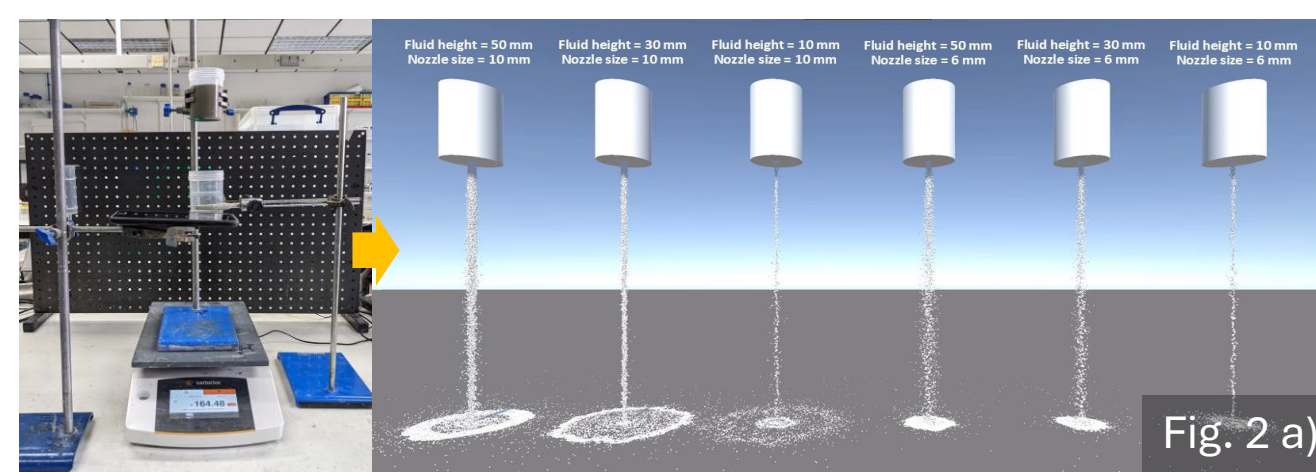


Fig. 2 Position-based Fluid simulation to inform physical robotic crack sealing operations: a) Transfer the physical sealant flow behaviour to simulated sealants using an agile flow cup test; and b) Map the simulated robotic crack sealing process (using the learned sealant flow behaviour) with the reality in the lab.

## Develop the digital AMP concept

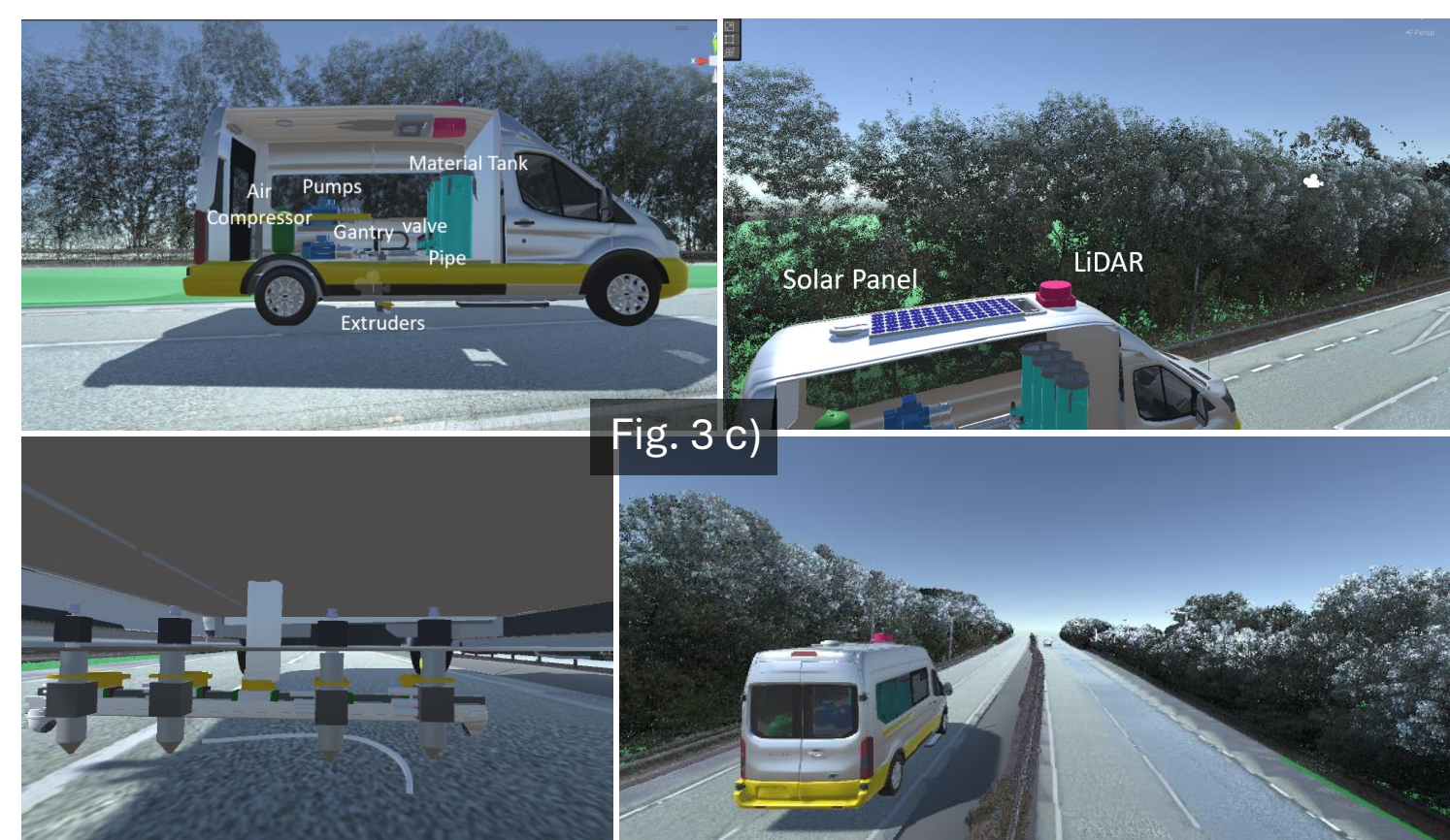
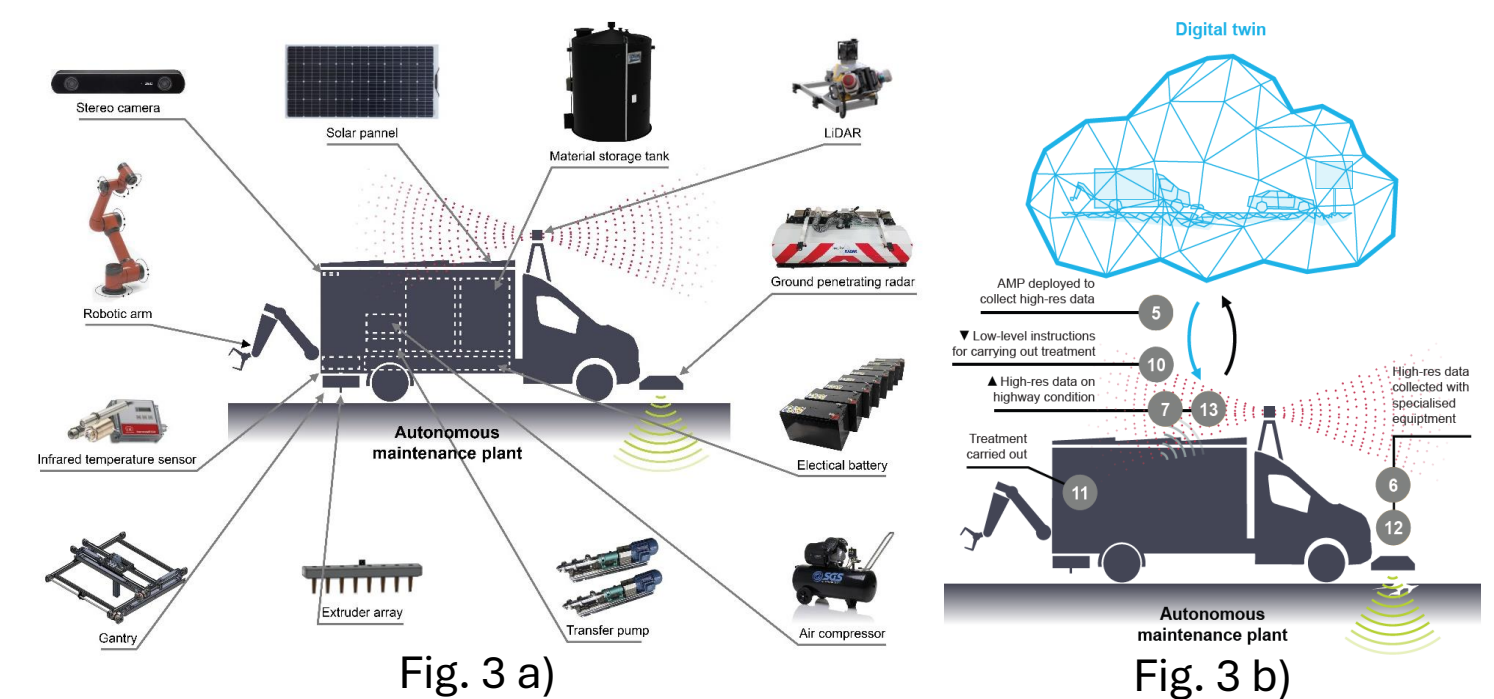


Fig. 3 Conceptual Autonomous Maintenance Plant (AMP) system for autonomous pavement crack repair: a) AMP system composition, mainly consisting of five modules for sensing, actuation, control, power supply and mobility; b) Digital workflow of the AMP including high-resolution surface sensing and autonomous crack repair operations, enabled (instructed) by the road digital twin; and c) different views of the AMP system in Unity simulation.

## What next?

Plan for the coming 12 months:

- Develop low-hanging fruit proof-of-concept enhanced asphalt road repair materials
- Verified durability of repaired defect samples
- Establish fast sealant fluid fillability benchmarking test using simulation
- Automated crack trajectory planning and following
- Integrate the conceptual AMP systems with robotic repair mechanism

## Acknowledgements

This work is supported by the Engineering and Physical Sciences Research Council [EP/V056441/1].

## References:

- (1) Palin, D.; Abdalgadir, H. T.; Vlachakis, C.; Rengaraju, S.; Hadjidemetriou, G. M.; d'Avigneau, A. M.; Anvo, N. R.; Girolami, M.; Al-Tabbaa, A. Evaluation of concrete road repair materials durability via DIC.
- (2) Schaefer, S.; Palin, D.; Hadjidemetriou, G. M.; Ambrose, M.; Iida, F.; Al-Tabbaa, A.; Thuruthel, T. G. Robotic Maintenance and Repair of Roads: A Systematic Review, *submitted*.
- (3) Schaefer, S. D., Xu, J., Palin, D., Al-Tabbaa, A., & Iida, F. (2024). Position-based fluid simulation for robotic injection sealing of pavement cracks. *Journal of Field Robotics*.
- (4) Xu, J., Anvo, N. Z. R., Taha, H. M., d'Avigneau, A. M., Palin, D., Wei, R., Hadjidemetriou, G., Schaefer, S., Silva, L., Al-Tabbaa, A., Iida, F., & Brilakis, B. (2024) Highway digital twin-enabled Autonomous Maintenance Plant (AMP): A perspective. *Data-Centric Engineering*.