

# Establishing DT Information Requirements for Road Maintenance

Varun Kumar Reja, Ioannis Brilakis, Kristen MacAskill

## Background & Motivation

- Current workflows lack autonomy – Laborious
- Data Silos and Inconsistency – Inefficient
- Reactive Maintenance Practices – Unsafe

Digital Twins (DT) Technology holds huge potential for revamping road asset maintenance.

- No Defined set of requirements for generating a minimum viable DT.

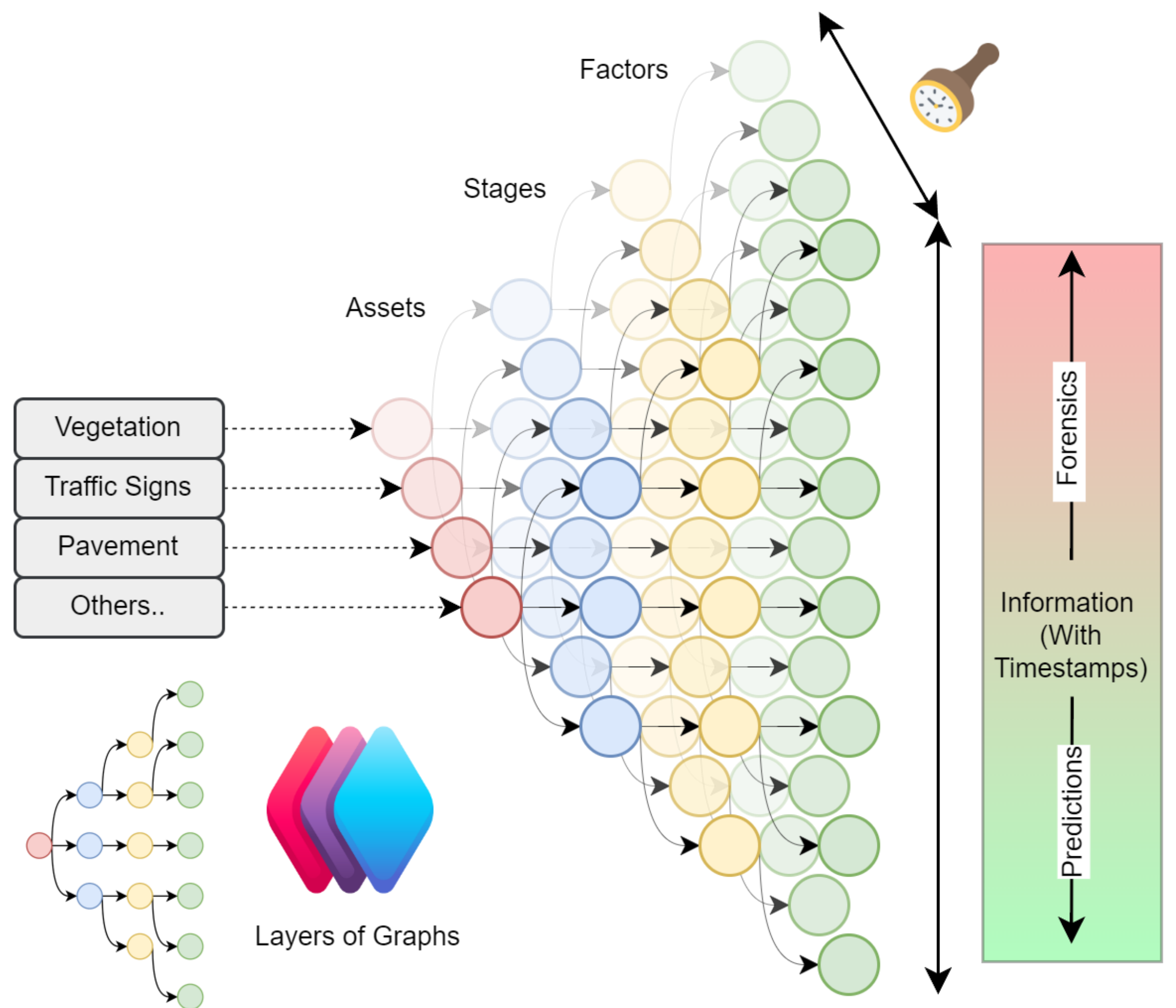
## Objectives

1. Map the current states of processes and identify specific challenges in road asset maintenance.
2. Develop a framework for the Digital Twin Information Requirements (IR) Model.
3. Define stages and influencing factors and determine the corresponding information requirements for each road asset.

## Research Summary

- Developed a specific methodology for establishing information requirements.
- Defined a framework for the architecture of a highway DT based on the information Requirements.
- Established Overgrown Vegetation DT Information Requirements and demonstrated a use case on a real-world dataset using computer vision technology [1].
- Established Traffic Signs Data Requirements and used it to model the traffic signs for a submitted work.

## Architecture of Highway Digital Twin



## What next?

Establish IR for the following Assets:

1. Roadside Vegetation (Completed)
2. Traffic Signs (Completed)
3. Pavement (In Progress)
4. Road Markings
5. Road Lights
6. Drainage

## Acknowledgements

This work was supported by the European Union's Horizon 2020 research and innovation programme under the Marie Skłodowska-Curie [Grant Agreement No 101034337]. Thanks to the International & Industry Supervisors M. Hunter, J. Morley, Y. Patel, M. Peck, N. Wang, A. Hagen, S. Hayton, M. Pelken, T. Tideswell, J. Flint, F. Perrota, J. Simons, J. Locke, G. Economides, M. Fisher, S. Oueltdimijja, E. Wells.

## References

1. V.K. Reja, D. Davletshina, M. Yin, R. Wei, Q. F. Adam, I. Brilakis, F. Perrota, A Digital Twin Based Approach to Control Overgrowth of Roadside Vegetation, Proceedings of the 41st International Symposium on Automation and Robotics in Construction (ISARC 2024), 3-5 June 2024, Lille, France.